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1. Introduction

Recently, Compressed Sensing (Compressive Sampling) has attracted a lot of attention of both mathematicians and computer scientists. Compressed Sensing refers to a problem of economical recovery of an unknown vector \( u \in \mathbb{R}^m \) from the information provided by linear measurements \( \langle u, \varphi_j \rangle, \varphi_j \in \mathbb{R}^m, j = 1, \ldots, n \). The goal is to design an algorithm that finds (approximates) \( u \) from the information \( y = (\langle u, \varphi_1 \rangle, \ldots, \langle u, \varphi_n \rangle) \in \mathbb{R}^n \). We note that the most important case is when the number of measurements \( n \) is much smaller than \( m \). The crucial step here is to build a sensing set of vectors \( \varphi_j \in \mathbb{R}^m, j = 1, \ldots, n \) that is good for all vectors \( u \in \mathbb{R}^m \). Clearly, the terms economical and good should be clarified in a mathematical setting of the problem. For instance, economical may mean a polynomial time algorithm. A natural variant of such setting, that is discussed here, uses the concept of sparsity. Sparse representations of a function are not only a powerful analytic tool but they are utilized in many application areas such as image/signal processing and numerical computation. The backbone of finding sparse representations is the concept of \( m \)-term approximation of the target function by the elements of a given system of functions (dictionary). Since the elements of the dictionary used in the \( m \)-term approximation are allowed to depend on the function being approximated, this type of approximation is very efficient. We call a vector \( u \in \mathbb{R}^m \) \( k \)-sparse if it has at most \( k \) nonzero coordinates. Now, for a given pair \((m, n)\) we want to understand what is the biggest sparsity \( k(m, n) \) such that there exists a set of vectors \( \varphi_j \in \mathbb{R}^m, j = 1, \ldots, n \) and an economical algorithm \( A \) mapping \( y \) into \( \mathbb{R}^m \) in such a way that for any \( u \) of sparsity \( k(m, n) \) one would have an exact recovery \( A(u) = u \). In other words, we want to describe matrices \( \Phi \) with rows \( \varphi_j \in \mathbb{R}^m, j = 1, \ldots, n \), such that there exists an economical algorithm of solving the following sparse recovery problem.

The sparse recovery problem can be stated as the problem of finding the sparsest vector \( u^0 := u^0_\Phi(y) \in \mathbb{R}^m \):

\[
(P_0) \quad \min \|v\|_0 \quad \text{subject to} \quad \Phi v = y,
\]

where \( \|v\|_0 := |\text{supp}(v)| \). D. Donoho with coauthors (see, for instance, [CDS] and [DET] and history therein) have suggested an economical algorithm and have begun a systematic

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study of the following question. For which measurement matrices $\Phi$ the highly non-convex combinatorial optimization problem $(P_0)$ should be equivalent to its convex relaxation problem

$$(P_1) \quad \min \|v\|_1 \text{ subject to } \Phi v = y,$$

where $\|v\|_1$ denotes the $\ell_1$-norm of the vector $v \in \mathbb{R}^m$? It is known that the problem $(P_1)$ can be solved by linear programming technique. The $\ell_1$-minimization algorithm $A_{\Phi}$ from $(P_1)$ is an economical algorithm that we consider in this paper. Denote the solution to $(P_1)$ by $A_{\Phi}(y)$. It is known (see, for instance, [DET]) that for $M$-coherent matrices $\Phi$ one has $u^0_\Phi(\Phi u) = A_{\Phi}(\Phi u) = u$ provided $u$ is $k$-sparse with $k < (1 + 1/M)/2$. This allows us to build rather simple deterministic matrices $\Phi$ with $k(m, n) \approx n^{1/2}$ and recover with the $\ell_1$-minimization algorithm $A_{\Phi}$ from $(P_1)$.

Recent progress (see surveys [C], [D]) in Compressed Sensing resulted in proving the existence of matrices $\Phi$ with $k(m, n) \approx n/\log(m/n)$ which is substantially larger than $n^{1/2}$. A number of authors (see, for instance, [Do], [CDD]) have pointed out a connection between the Compressed Sensing problem and the problem of estimating the widths of finite dimensional sets, studied at the end of seventies and the beginning of eighties of the 20th century. In this paper we make the above mentioned connection more precise. We proceed to a detailed discussion of recent results.

We begin with results from [Do]. D. Donoho [Do] formulated the following three properties of matrices $\Phi$ with normalized in $\ell_2$ columns and proved existence of matrices satisfying these conditions. Let $T$ be a subset of indices from $[1, m]$. Denote $\Phi_T$ a matrix consisting of columns of $\Phi$ with indices from $T$.

**CS1.** The minimal singular value of $\Phi_T$ is $\geq \eta_1 > 0$ uniformly in $T$, satisfying $|T| \leq \rho n/\log m$.

**CS2.** Let $W_T$ denote the range of $\Phi_T$. Assume that for any $T$ satisfying $|T| \leq \rho n/\log m$ one has

$$\|w\|_1 \geq \eta_2 n^{1/2}\|w\|_2, \quad \forall w \in W_T, \quad \eta_2 > 0.$$

**CS3.** Denote $T^c := \{j \in [1, m] \setminus T\}$. For any $T$, $|T| \leq \rho n/\log m$ and for any $w \in W_T$ one has for any $v$ satisfying $\Phi_{T^c} v = w$

$$\|v\|_{\ell_1(T^c)} \geq \eta_3 (\log(m/n))^{-1/2}\|w\|_1, \quad \eta_3 > 0.$$

It is proved in [Do] that if $\Phi$ satisfies **CS1−CS3** then there exists $\rho_0 > 0$ such that $u^0_\Phi(\Phi u) = A_{\Phi}(\Phi u) = u$ provided $|\text{supp } u| \leq \rho_0 n/\log m$. Analysis in [Do] relates the Compressed Sensing problem to the problem of estimating the Kolmogorov widths and their dual - the Gel’fand widths.

We give the corresponding definitions. For a compact $F \subset \mathbb{R}^m$ the Kolmogorov width

$$d_n(F, \ell_p) := \inf_{L_n : \dim L_n \leq n} \sup_{f \in F} \inf_{a \in L_n} \|f - a\|_p,$$
where $L_n$ is a linear subspace of $\mathbb{R}^m$ and $\| \cdot \|_p$ denotes the $\ell_p$-norm. The Gel’fand width is defined as follows

$$d_n(F, \ell_p) := \inf_{V_n} \sup_{f \in F \cap V_n} \| f \|_p,$$

where infimum is taken over linear subspaces $V_n$ with dimension $\geq m - n$. It is well known that the Kolmogorov and the Gel’fand widths are related by the duality formula. S.M. Nikol’skii was the first to use the duality idea in approximation theory. For instance (see [I]), in the case of $F = B_p^m$ is a unit $\ell_p$-ball in $\mathbb{R}^m$ and $1 \leq q, p \leq \infty$ one has

(1.1) \[ d_n(B_p^m, \ell_q) = d_n(B_{q'}^m, \ell_{p'}), \quad p' := p/(p - 1). \]

In a particular case $p = 2$, $q = \infty$ of our interest (1.1) gives

(1.2) \[ d_n(B_2^m, \ell_\infty) = d_n(B_2^m, \ell_2). \]

It has been established in approximation theory (see [K] and [GG]) that

(1.3) \[ d_n(B_2^m, \ell_\infty) \leq C((1 + \log(m/n))/n)^{1/2}. \]

By $C$ we denote here and in the whole paper an absolute constant. In other words, it was proved (see (1.3) and (1.2)) that for any pair $(m, n)$ there exists a subspace $V_n$, $\dim V_n \geq m - n$ such that for any $x \in V_n$ one has

(1.4) \[ \| x \|_2 \leq C((1 + \log(m/n))/n)^{1/2}\| x \|_1. \]

It has been understood in [Do] that properties of the null space $\mathcal{N}(\Phi) := \{ x : \Phi x = 0 \}$ of a measurement matrix $\Phi$ play an important role in the Compressed Sensing problem. D. Donoho introduced in [Do] the following two characteristics associated with $\Phi$ that are formulated in terms of $\mathcal{N}(\Phi)$:

$$w(\Phi, F) := \sup_{x \in F \cap \mathcal{N}(\Phi)} \| x \|_2$$

and

$$\nu(\Phi, T) := \sup_{x \in \mathcal{N}(\Phi)} \| x_T \|_1/\| x \|_1,$$

where $x_T$ is a restriction of $x$ onto $T$: $(x_T)_j = x_j$ for $j \in T$ and $(x_T)_j = 0$ otherwise. He proved that if $\Phi$ obeys the following two conditions

(A1) \[ \nu(\Phi, T) \leq \eta_1, \quad |T| \leq \rho_1 n/ \log m; \]

(A2) \[ w(\Phi, B_1^m) \leq \eta_2((\log m_n)/n)^{1/2}, \quad m_n \asymp n^\gamma, \quad \gamma > 0; \]
then for any \( u \in B_1^m \) we have

\[
\|u - A \Phi(\Phi u)\|_2 \leq C((\log m_n)/n)^{1/2}.
\]

We now proceed to the contribution of E. Candes, J. Romberg, and T. Tao published in a series of papers. They (see [CD]) introduced the following Restricted Isometry Property (RIP) of a sensing matrix \( \Phi \): \( \delta_S < 1 \) is the \( S \)-restricted isometry constant of \( \Phi \) if it is the smallest quantity such that

\[
(1 - \delta_S)\|c\|_2^2 \leq \|\Phi T c\|_2^2 \leq (1 + \delta_S)\|c\|_2^2
\]

for all subsets \( T \) with \( |T| \leq S \) and all coefficient sequences \( \{c_j\}_{j \in T} \). Candes and Tao ([CD]) proved that if \( \delta_{2S} + \delta_{3S} < 1 \) then for \( S \)-sparse \( u \) one has \( A \Phi(\Phi u) = u \) (recovery by \( \ell_1 \)-minimization is exact). They also proved existence of sensing matrices \( \Phi \) obeying the condition \( \delta_{2S} + \delta_{3S} < 1 \) for large values of sparsity \( S \approx n/(1 + \log m/n) \). For a positive number \( a \) denote

\[
\sigma_a(v)_1 := \min_{w \in \mathbb{R}^m : |\text{supp}(w)| \leq a} \|v - w\|_1.
\]

In [CRT] the authors proved that if \( \delta_{3S} + 3\delta_{4S} < 2 \), then

\[
\|u - A \Phi(\Phi u)\|_2 \leq CS^{-1/2}\sigma_S(u)_1.
\]

We note that properties of the RIP-type matrices have already been employed in [K] for the widths estimation. The inequality (1.3) with an extra factor \((1 + \log m/n)\) has been established in [K]. The proof in [K] is based on properties of a random matrix \( \Phi \) with elements \( \pm 1/\sqrt{n} \). It has been proved in [K] that a random matrix with elements \( \pm 1/\sqrt{n} \) satisfies (with positive probability) the left-hand inequality in (1.5) for \( S \approx n/(1 + \log m/n) \) (see (13) and (30) in [K]). It was also proved in [K] that this matrix satisfies the inequality

\[
\|\Phi T c\|_2^2 \leq C(1 + \log m/n)\|c\|_2^2
\]

for any subset \( T \) with \( |T| \leq n \) and any set of coefficients \( \{c_j\}_{j \in T} \) (see (29) in [K]). We note that the proof of the right-hand inequality in (1.5) with \( S \approx n/(1 + \log m/n) \) for a random \( n \times m \) matrix with elements \( \pm 1/\sqrt{n} \) could be done in a way similar to the proof of (1.7).

In Section 3 we give an elaboration of the argument in [K] that allows us to get rid of the extra log-factor in the estimate of \( d_n(B_2^m, \ell_\infty^n) \) proved in [K]. We note that this argument does not use the duality formula contrary to the first proof of the sharp result from [GG].

Further investigation of the Compressed Sensing problem has been conducted by A. Cohen, W. Dahmen, and R. DeVore ([CDD]). They proved that if \( \Phi \) satisfies the RIP of order \( 2k \) with \( \delta_{2k} < \delta < 1/3 \) then one has

\[
\|u - A \Phi(\Phi u)\|_1 \leq \frac{2 + 2\delta}{1 - 3\delta}\sigma_k(u)_1.
\]
In the proof of (1.8) the authors used the following property (null space property) of matrices Φ satisfying RIP of order 3k/2: for any \( x \in \mathcal{N}(\Phi) \) and any \( T \) with \( |T| \leq k \) we have

\[
\|x\|_1 \leq C\|x_Tc\|_1.
\]

The null space property (1.9) is closely related to the property \((A1)\) from [Do]. The proof of (1.8) from [CDD] gives similar to (1.8) inequality under assumption that Φ has null space property (1.9) with \( C < 2 \).

We now discuss results of this paper. We say that a measurement matrix Φ has a Strong Compressed Sensing Property (SCSP) if for any \( u \in \mathbb{R}^m \) we have

\[
\|u - A \Phi (\Phi u)\|_2 \leq C k^{-1/2} \sigma_k(u)_1
\]

for \( k \approx n/ \log(m/n) \). We define a Weak Compressed Sensing Property (WCSP) by replacing (1.10) by the weaker inequality

\[
\|u - A \Phi (\Phi u)\|_2 \leq C k^{-1/2} \|u\|_1.
\]

We say that \( \Phi \) satisfies the Width Property (WP) if (1.4) holds for the null space \( \mathcal{N}(\Phi) \).

The main result of our paper states that the above three properties of \( \Phi \) are equivalent. The equivalence is understood in the following way. For example, we say that the WCSP implies the SCSP if (1.11) with a constant \( C \) implies (1.10) with other constant \( C' \). We stress that we are interested here in the asymptotic behavior of the quantities as \( m \) and \( n \) go to infinity.

2. New results

We mentioned in the Introduction that it is known that for any pair \((m, n), n < m\), there exists a subspace \( \Gamma \subset \mathbb{R}^m \) with \( \dim \Gamma \geq m - n \) such that

\[
\|x\|_2 \leq C n^{-1/2} (\ln(em/n))^{1/2} |x|_1, \quad \forall x \in \Gamma.
\]

We will study some properties of subspaces \( \Gamma \) satisfying (2.1) that are useful in compressed sensing. Denote

\[
S := S(m, n) := C^{-2} n (\ln(em/n))^{-1}.
\]

For \( x = (x_1, \ldots, x_m) \in \mathbb{R}^m \) denote \( \text{supp}(x) := \{ j : x_j \neq 0 \} \).

**Lemma 2.1.** Let \( \Gamma \) satisfy (2.1) and \( x \in \Gamma \). Then either \( x = 0 \) or \( |\text{supp}(x)| \geq S(m, n) \).

**Proof.** Assume \( x \neq 0 \). Then \( \|x\|_1 > 0 \). Denote \( \Lambda := \text{supp}(x) \). We have

\[
\|x\|_1 = \sum_{j \in \Lambda} |x_j| \leq |\Lambda|^{1/2} \left( \sum_{j \in \Lambda} |x_j|^2 \right)^{1/2} \leq |\Lambda|^{1/2} \|x\|_2.
\]

Using (2.1) we get from (2.2)

\[
\|x\|_1 \leq |\Lambda|^{1/2} S(m, n)^{-1/2} \|x\|_2.
\]

Thus

\[
|\Lambda| \geq S(m, n).
\]
Lemma 2.2. Let $\Gamma$ satisfy (2.1) and let $x \neq 0$, $x \in \Gamma$. Then for any $\Lambda$ such that $|\Lambda| < S(m,n)/4$ one has
\[
\sum_{j \in \Lambda} |x_j| < \|x\|_1/2.
\]

Proof. Similar to (2.2)
\[
\sum_{j \in \Lambda} |x_j| \leq |\Lambda|^{1/2} S(m,n)^{-1/2} \|x\|_1 < \|x\|_1/2.
\]

Lemma 2.3. Let $\Gamma$ satisfy (2.1). Suppose $u \in \mathbb{R}^m$ is sparse with $|\text{supp}(u)| < S(m,n)/4$. Then for any $v = u + x$, $x \in \Gamma$, $x \neq 0$, one has
\[
\|v\|_1 > \|u\|_1.
\]

Proof. Let $\Lambda := \text{supp}(u)$. Then
\[
\|v\|_1 = \sum_{j \in [1,m]} |v_j| = \sum_{j \in \Lambda} |u_j + x_j| + \sum_{j \notin \Lambda} |x_j| \geq \sum_{j \in \Lambda} |u_j| - \sum_{j \in \Lambda} |x_j| + \sum_{j \notin \Lambda} |x_j| = \|u\|_1 + \|x\|_1 - 2 \sum_{j \in \Lambda} |x_j|.
\]

By Lemma 2.2
\[
\|x\|_1 - 2 \sum_{j \in \Lambda} |x_j| > 0.
\]

Lemma 2.3 guarantees that the following algorithm, known as the Basis Pursuit (see $A_\Phi$ from the Introduction), will find a sparse $u$ exactly, provided $|\text{supp}(u)| < S(m,n)/4$:
\[
u_\Gamma := u + \arg \min_{x \in \Gamma} \|u + x\|_1.
\]

Theorem 2.1. Let $\Gamma$ satisfy (2.1). Then for any $u \in \mathbb{R}^m$ and $u'$ such that $\|u'\|_1 \leq \|u\|_1$, $u - u' \in \Gamma$ one has
\[
\|u - u'\|_1 \leq 4\sigma_{S/16}(u)_1,
\]
\[
\|u - u'\|_2 \leq (S/16)^{-1/2}\sigma_{S/16}(u)_1.
\]

Proof. It is given that $u - u' \in \Gamma$. Thus, (2.4) follows from (2.3) and (2.1). We now prove (2.3). Let $\Lambda$, $|\Lambda| = [S/16]$, be the set of indices of biggest in absolute value coordinates of
Therefore, above statement.

We have

\[ \|u - u'\|_1 \leq \|(u - u')_\Lambda\|_1 + \|(u - u')_A\|_1. \]

Next,

\[ \|(u - u')_A\|_1 \leq \|u'_A\|_1 + \|(u')_A\|_1. \]

Using \(\|u'_1\| \leq \|u\|\), we obtain

\[ \|(u')_A\|_1 - \|u'_A\|_1 = \|u'_1\| - \|u\| - \|u'_A\|_1 + \|u_A\|_1 \leq \|(u - u')_\Lambda\|_1. \]

Therefore,

\[ \|(u')_A\|_1 \leq \|u'_A\|_1 + \|(u - u')_\Lambda\|_1 \]

and

\[ \|u - u'\|_1 \leq 2\|(u - u')_\Lambda\|_1 + 2\|u_A\|_1. \]

Using the fact \(u - u' \in \Gamma\) we estimate

\[ \|(u - u')_\Lambda\|_1 \leq |\Lambda|^{1/2}\|(u - u')_\Lambda\|_2 \leq |\Lambda|^{1/2}\|u - u'\|_2 \leq |\Lambda|^{1/2}S^{-1/2}\|u - u'\|_1. \]

Our assumption on \(|\Lambda|\) guarantees that \(|\Lambda|^{1/2}S^{-1/2} \leq 1/4\). Using this and substituting (2.7) into (2.6) we obtain

\[ \|u - u'\|_1 \leq \|u - u'\|_1/2 + 2\|u_A\|_1 \]

which gives (2.3):

\[ \|u - u'\|_1 \leq 4\|u_A\|_1. \]

**Corollary 2.1.** Let \(\Gamma\) satisfy (2.1). Then for any \(u \in \mathbb{R}^m\) one has

\[ \|u - u_\Gamma\|_1 \leq 4\sigma_{S/16}(u)_1. \]

\[ \|u - u_\Gamma\|_2 \leq (S/16)^{-1/2}\sigma_{S/16}(u)_1. \]

**Proposition 2.1.** Let \(\Gamma\) be such that (1.11) holds with \(u_\Gamma\) instead of \(A_\Phi(u_\Phi)\) and \(k = n/\ln(em/n)\). Then \(\Gamma\) satisfies (2.1).

**Proof.** Let \(u \in \Gamma\). Then \(u_\Gamma = 0\) and we get from (1.11)

\[ \|u\|_2 \leq C(n/\ln(em/n))^{-1/2}\|u\|_1. \]

**Theorem 2.2.** The following three properties of \(\Phi\) are equivalent: Strong Compressed Sensing Property, Weak Compressed Sensing Property, Width Property.

**Proof.** It is obvious that SCSP \(\Rightarrow\) W SCP. Corollary 2.1 with \(\Gamma = \mathcal{N}(\Phi)\) implies that WP \(\Rightarrow\) SCSP. Proposition 2.1 with \(\Gamma = \mathcal{N}(\Phi)\) implies that W SCP \(\Rightarrow\) WP. Thus the three properties are equivalent.

The result (1.8) of [CRT] states that RIP with \(S \approx n/\log(m/n)\) implies the SCSP. Therefore, by Theorem 2.2 it implies the WP. We give in Section 3 a direct proof of the above statement.
3. A direct proof that RIP implies WP

We will show that any subspace \( L \subset \mathbb{R}^m \) that is generated by a matrix \( \Phi \) of the rank \( n \) (\( L \) is spanned by the rows of \( \Phi \)) that satisfies (1.5) with \( S \approx n/(1 + \log m/n) \) approximates in \( \ell_\infty \) metric the Euclidean ball with the optimal error:

\[
d(B_2^m, L)_{\ell_\infty} \leq Cn^{-1/2}(1 + \log m/n)^{1/2}. \tag{3.1}
\]

We can assume that any \( n \) columns of the matrix \( \Phi \) are linearly independent (we always can achieve this by an arbitrarily small change in the elements of matrix \( \Phi \)). Let \( e_1, \ldots, e_m \) be the columns of matrix \( \Phi \). Then it is sufficient to prove (see [K]) that for any decomposition

\[
e_{i_{n+1}} = \sum_{s=1}^{n} \lambda_s e_{i_s}, \quad i_\nu \neq i_\mu \text{ if } \nu \neq \mu, \ 1 \leq \nu, \mu \leq n + 1, \tag{3.2}
\]

the inequality

\[
\frac{\|\lambda\|_2}{\|\lambda\|_1} \left(1 + \frac{1}{\|\lambda\|_2}\right) \leq Cn^{-1/2}(1 + \log m/n)^{1/2}, \quad \lambda = (\lambda_1, \ldots, \lambda_n), \tag{3.3}
\]

holds. Let us rewrite (3.2) as follows:

\[
\sum_{s=1}^{n+1} \bar{\lambda}_s e_{i_{\sigma(s)}} = 0
\]

where

\[
|\bar{\lambda}_1| \geq \cdots \geq |\bar{\lambda}_{n+1}|
\]

and among the coordinates of vector \( \bar{\lambda} = \{\bar{\lambda}_s\}_{s=1}^{n+1} \) there is 1 and all the \( \lambda_i, 1 \leq i \leq n \).

By repeating the reasoning of Lemma 4.1 from [CDD] (see also Lemma 3 in [GG], [CRT]), we obtain from (1.5) for \( S \approx n/(1 + \log m/n) \)

\[
\begin{aligned}
&\left(\sum_{s=1}^{4S} \bar{\lambda}_s^2\right)^{1/2} \leq C'S^{-1/2} \sum_{s=1}^{n+1} |\bar{\lambda}_s|, \\
&\sum_{s=1}^{n+1} |\bar{\lambda}_s| \leq C \sum_{s=S+1}^{n} |\bar{\lambda}_s|.
\end{aligned} \tag{3.4}
\]

From (3.4) it follows that

\[
\|\bar{\lambda}\|_2 \leq CS^{-1/2}\|\bar{\lambda}\|_1. \tag{3.5}
\]

If (3.5) were not true, then the ‘positive share’ of \( \ell^2 \)-norm of the vector \( \bar{\lambda} \) would be located on the first \( 4S \) coordinates (see Lemma 4 in [K]), which contradicts (3.4).

Besides, because \( \|\bar{\lambda}\|_2 > 1 \), from (3.5) we obtain \( \|\bar{\lambda}\|_1 \geq cS^{1/2} \), and, therefore, \( \|\lambda\|_1 \geq cS^{1/2} \). Finally,

\[
\frac{\|\lambda\|_2}{\|\lambda\|_1} \leq \frac{\|\bar{\lambda}\|_2}{\|\bar{\lambda}\|_1} \leq \frac{2\|\bar{\lambda}\|_2}{\|\bar{\lambda}\|_1} \leq 2CS^{-1/2},
\]

which is what we needed to prove.
References


